

Smoluchowski Equation from Overdamped Langevin equation

Recall Langevin eqn in Force field:

$$m\ddot{x} = \underbrace{-m\zeta\dot{x}}_{\text{Friction}} + \underbrace{F(x)}_{\text{External force}} + \underbrace{f(t)}_{\text{stochastic force.}}$$

With strong damping  $m\zeta\dot{x} \gg m\ddot{x}$ , L. equation becomes,

$$0 = -m\zeta\dot{x} + F(x) + f(t)$$

$$\dot{x} = \frac{F(x)}{m\zeta} + \frac{f(t)}{m\zeta}$$

$$= -\frac{1}{m\zeta} \frac{\partial V}{\partial x} + \frac{f(t)}{m\zeta} \quad \text{Solution: } \Delta x(t) = \frac{1}{m\zeta} \int_0^t dt' \left( \frac{\partial V}{\partial x} + f(t') \right)$$

Given an initial coordinate distribution,  $P(x, t_0)$ , the distribution evolves through time due to Brownian motion:

$$\text{Define } P(x, t) = \langle \delta(x - x(t)) \rangle \quad (\text{Ensemble average})$$

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Stochastic variable  
(one function  $x(t)$  for one system in an ensemble) — a single realization.

Derive an equation of motion for  $P(x, t)$ . (How does  $P$  evolve?)

$$\frac{\partial}{\partial t} P(x, t) = \frac{\partial}{\partial t} \langle \delta(x - x(t)) \rangle \quad \text{use } \frac{\partial}{\partial t} = \frac{\partial x}{\partial t} \frac{\partial}{\partial x} = \frac{\partial x}{\partial t} \frac{\partial}{\partial x}$$

$$= -\frac{\partial}{\partial x} \langle \delta(x - x(t)) \frac{\partial x}{\partial t} \rangle \quad \text{Langevin: } \frac{\partial x}{\partial t} = -\frac{1}{m\zeta} \frac{\partial V}{\partial x} + \frac{f(t)}{m\zeta}$$

$$= -\frac{\partial}{\partial x} \langle \delta(x - x(t)) \left( -\frac{1}{m\zeta} \frac{\partial V}{\partial x} + \frac{f(t)}{m\zeta} \right) \rangle$$

$$= -\frac{\partial}{\partial x} \langle \delta(x - x(t)) \frac{\partial V}{\partial x} \rangle \times \frac{-1}{m\zeta} - \frac{\partial}{\partial x} \langle \delta(x - x(t)) \frac{f(t)}{m\zeta} \rangle$$

$$= \frac{1}{m\zeta} \frac{\partial}{\partial x} \left[ \underbrace{\langle \delta(x - x(t)) \rangle}_{P(x, t)} \frac{\partial V}{\partial x} \right] - \frac{1}{m\zeta} \frac{\partial}{\partial x} \langle \delta(x - x(t)) f(t) \rangle \quad \text{Simplify.}$$

Just like in deriving the Fokker-Planck Equation,

$$\text{Use } P[f(t)] = e^{-\int_{t_i}^{t_f} dt \frac{1}{2} \frac{1}{2m\epsilon k_B T} f^2(t)}$$

$$\begin{aligned} \text{Define: } Z[j(t)] &= \int \mathcal{D}f(t) e^{-\int_{t_i}^{t_f} dt \left( \frac{1}{2} f(t) \frac{1}{2m\epsilon k_B T} f(t) + j(t)f(t) \right)} \\ &= e^{-\int_{t_i}^{t_f} dt dt' \frac{1}{2} j(t) \frac{1}{2m\epsilon k_B T} \delta(t-t') j(t')} \end{aligned}$$

So, we need

$$\begin{aligned} -\frac{1}{m\epsilon} \langle \delta(x - x(t)) f(t) \rangle &= -\frac{1}{m\epsilon} \int \mathcal{D}f(t') \delta(x - x(t)) f(t) e^{-\int_{t_i}^{t_f} dt' \frac{1}{2} f(t') \frac{1}{2m\epsilon k_B T} f(t')} \\ &= \frac{+1}{m\epsilon} \left( +2m\epsilon k_B T \right) \int \mathcal{D}f(t') \delta(x - x(t)) \frac{\delta}{\delta f(t)} e^{-\int_{t_i}^{t_f} dt' \frac{1}{2} f(t') \frac{1}{2m\epsilon k_B T} f(t')} \end{aligned}$$

Now perform a functional integration by parts.

$$= -2k_B T \int \mathcal{D}f(t') \frac{\delta}{\delta f(t)} \delta(x - x(t)) e^{-\int_{t_i}^{t_f} \dots}$$

$$= -2k_B T \left\langle \frac{\delta}{\delta f(t)} \delta(x - x(t)) \right\rangle \quad \frac{\delta}{\delta f(t)} = \frac{\delta x(t)}{\delta f(t)} \frac{\partial}{\partial x} = \frac{\delta x}{\delta f(t)} \frac{\partial}{\partial x}$$

$$= +2k_B T \frac{\partial}{\partial x} \left\langle \frac{\delta x(t)}{\delta f(t)} \delta(x - x(t)) \right\rangle$$

Use solution

$$x(t) = \frac{1}{m\epsilon} \int_0^t dt' \left( \frac{\partial V}{\partial x} + f(t') \right)$$

$$\text{Then } \frac{\delta x(t)}{\delta f(t)} = \frac{1}{m\epsilon} \int_0^t dt' \delta(t-t') = \frac{1}{2m\epsilon} \quad (\text{half delta})$$

$$= \frac{2k_B T}{2m\epsilon} \frac{\partial}{\partial x} \langle \delta(x - x(t)) \rangle = \frac{k_B T}{m\epsilon} \frac{\partial P(x,t)}{\partial x}$$

So,

$$\boxed{\frac{\partial P(x,t)}{\partial t} = \frac{1}{m\epsilon} \frac{\partial}{\partial x} \left[ P(x,t) \frac{\partial V}{\partial x} \right] + \frac{k_B T}{m\epsilon} \frac{\partial^2}{\partial x^2} P(x,t)}$$

Smoluchowski equation

The Smoluchowski equation can be cast as a continuity equation:

$$\frac{\partial P}{\partial t} + \frac{\partial J(x,t)}{\partial x} = 0,$$

$$\text{where } J(x,t) = -\frac{1}{m\zeta} \left( \underbrace{P(x,t) \frac{\partial V}{\partial x}}_{\substack{\text{drift term} \\ -V\text{-dependent}}} + \underbrace{k_B T \frac{\partial}{\partial x} P(x,t)}_{\substack{\text{diffusion term} \\ -\text{temperature dep.}}} \right)$$

Solution  $P(x,t) \propto e^{-V/k_B T}$  is a stationary solution.

In this case  $J(x,t) = 0$ :

$$\begin{aligned} J &= -\frac{1}{m\zeta} \left( e^{-V/k_B T} \frac{\partial V}{\partial x} + k_B T \frac{\partial}{\partial x} e^{-V/k_B T} \right) \\ &= -\frac{1}{m\zeta} \left( e^{-V/k_B T} \frac{\partial V}{\partial x} + \frac{k_B T}{k_B T} \frac{-\partial V}{\partial x} e^{-V/k_B T} \right) \\ &= \frac{-1}{m\zeta} (0) = 0 \quad \checkmark \end{aligned}$$

Normalization:

$$\int P(x,t) dx = 1 \Rightarrow$$

$$P(x,t) = \frac{1}{\int dx e^{-V(x)/k_B T}} e^{-V(x)/k_B T}$$