

### Euclideanization of Maxwell Action

$$\begin{aligned}
 iS[A] &= i \int d^4x \quad -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} \\
 &= i \int d^4x \quad -\frac{1}{2} \partial_\mu A_\nu (\partial^\mu A^\nu - \partial^\nu A^\mu) \\
 &= i \int d^4x \quad -\frac{1}{2} \left[ \partial_0 A_i (\partial^0 A^i - \partial^i A^0) + \partial_i A_0 (\partial^i A^0 - \partial^0 A^i) + \partial_i A_j (\partial^i A^j - \partial^j A^i) \right] \\
 &\hspace{10em} \text{lower indices.} \\
 &= i \int d^4x \quad -\frac{1}{2} \left[ -\partial_0 A_i (\partial_0 A_i - \partial_i A_0) - \partial_i A_0 (\partial_i A_0 - \partial_0 A_i) + \partial_i A_j (\partial_i A_j - \partial_j A_i) \right]
 \end{aligned}$$

Euclideanize:

$$\left. \begin{aligned}
 &\text{Take } t = -i\tau \\
 &\text{and } A_0 = i\hat{A}_0 \quad A_i = \hat{A}_i \\
 &\text{(so that field eqns.} \\
 &\text{do not become complex)}
 \end{aligned} \right\}$$

$$\partial_0 = \frac{\partial}{\partial t} = \frac{\partial}{\partial(-i\tau)} = i \partial_\tau$$

$$\begin{aligned}
 \vec{E} &= -\vec{\nabla} A^0 - \frac{\partial \vec{A}}{\partial t} \\
 &= -i \vec{\nabla} \hat{A}^0 - i \frac{\partial \hat{A}}{\partial \tau} = i \vec{E} \\
 \vec{B} &= \vec{\nabla} \times \vec{A} = \hat{B}
 \end{aligned}$$

$$iS[A] \rightarrow i \int d(-i\tau) d^3x \quad -\frac{1}{2} \left[ -i \partial_\tau \hat{A}_i (i \partial_\tau \hat{A}_i - \partial_i (i \hat{A}_0)) - \partial_i (i \hat{A}_0) (\partial_i (i \hat{A}_0) - i \partial_0 A_i) + \partial_i A_j (\partial_i A_j - \partial_j A_i) \right]$$

$$= \int d\tau d^4x \quad \overset{\substack{\uparrow \\ \text{exponential} \\ \text{damping.}}}{+\frac{1}{2}} \left[ \partial_\tau \hat{A}_i (\partial_\tau \hat{A}_i - \partial_i \hat{A}_0) + \partial_i \hat{A}_0 (\partial_i \hat{A}_0 - \partial_\tau \hat{A}_i) + \partial_i \hat{A}_j (\partial_i \hat{A}_j - \partial_j \hat{A}_i) \right]$$

$\uparrow$  single  $\tau$ -derivative (removed in axial gauge)

$$= - \underbrace{\int (d^4x)_E}_{S_E[A]} \underbrace{\frac{1}{4} (\hat{F}_{\mu\nu} \hat{F}_{\mu\nu})}_{\mathcal{L}_E} = -S_E[A]$$

Axial gauge:  $\hat{A}_{\mu=0} = 0$

$$\hat{F}_{ij} = \partial_i \hat{A}_j - \partial_j \hat{A}_i$$

$$iS[A] = -S_E[A] = - \int (d^4x)_E \left[ \frac{1}{2} \left( \frac{\partial \hat{A}_i}{\partial \tau} \right)^2 + \frac{1}{2} \hat{F}_{ij} \hat{F}_{ij} \right].$$

Commutator of covariant derivatives

$$[D_\mu, D_\nu] = [\partial_\mu + ieA_\mu, \partial_\nu + ieA_\nu]$$

$$= \partial_\mu (ieA_\nu) - ieA_\nu \partial_\mu + ieA_\mu \partial_\nu - \partial_\nu (ieA_\mu)$$

$$= ie \partial_\mu A_\nu + ieA_\nu \partial_\mu - ieA_\nu \partial_\mu$$

$$+ ie \partial_\nu A_\mu - ie \partial_\nu A_\mu - ieA_\mu \partial_\nu$$

$$= ie (\partial_\mu A_\nu - \partial_\nu A_\mu)$$

$$= (F_{\mu\nu})_E$$