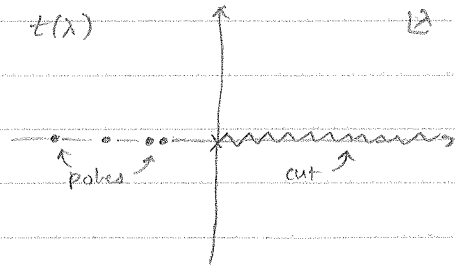


Transition Operator $\hat{E}(\lambda)$ [Off-shell \hat{T} matrix]

Definition:
$$\hat{E}(\lambda) = \hat{V} + \hat{V} \hat{G}(\lambda) \hat{V} = \underbrace{(\hat{1} + \hat{V} \hat{G}(\lambda)) \hat{V}}_{\text{[FORM I]}} = \hat{V} \underbrace{(\hat{1} + \hat{G}(\lambda) \hat{V})}_{\text{[FORM II]}}$$

Note: analytic structure of $\hat{E}(\lambda)$ is identical to that of $\hat{G}(\lambda)$



Multiply defⁿ FORM I at left by $\hat{G}_0(\lambda)$

Multiply defⁿ FORM II at right by $\hat{G}_0(\lambda)$

$$\hat{G}_0(\lambda) \hat{E}(\lambda) = \underbrace{[\hat{G}_0 + \hat{G}_0 \hat{V} \hat{G}(\lambda)]}_{\hat{G}(\lambda)} \hat{V} \quad \text{Lippmann-Schwinger for } \hat{G}(\lambda)$$

$$\hat{E}(\lambda) \hat{G}_0(\lambda) = \hat{V} \underbrace{[\hat{G}_0(\lambda) + \hat{G}(\lambda) \hat{V} \hat{G}_0(\lambda)]}_{\hat{G}(\lambda)}$$

$$\hat{G}_0(\lambda) \hat{E}(\lambda) = \hat{G}(\lambda) \hat{V} \quad (*)$$

$$\hat{E}(\lambda) \hat{G}_0(\lambda) = \hat{V} \hat{G}(\lambda) \quad (**)$$

↔ equivalent

Applications

① Plug (**) back into Lippmann-Schwinger eqn for $\hat{G}(\lambda)$:

$$\hat{G}(\lambda) = \hat{G}_0(\lambda) + \hat{G}_0(\lambda) \underbrace{\hat{V} \hat{G}(\lambda)}_{\hat{E}(\lambda) \hat{G}_0(\lambda)} \quad (**)$$

$$\hat{G}(\lambda) = \hat{G}_0(\lambda) + \hat{G}_0(\lambda) \hat{E}(\lambda) \hat{G}_0(\lambda)$$

means: knowledge of $\hat{E}(\lambda)$ implies knowledge of $\hat{G}(\lambda)$.

(that is, the definition of \hat{E} above leads to no loss of information about \hat{G})

② Plug (*) back into definition of $\hat{E}(\lambda)$:

$$\hat{E}(\lambda) = \hat{V} + \hat{V} \hat{G}(\lambda) \hat{V}$$

$$\boxed{\hat{E}(\lambda) = \hat{V} + \hat{V} \hat{G}_0(\lambda) \hat{E}(\lambda)}$$

Lippmann-Schwinger equation for $\hat{E}(\lambda)$.